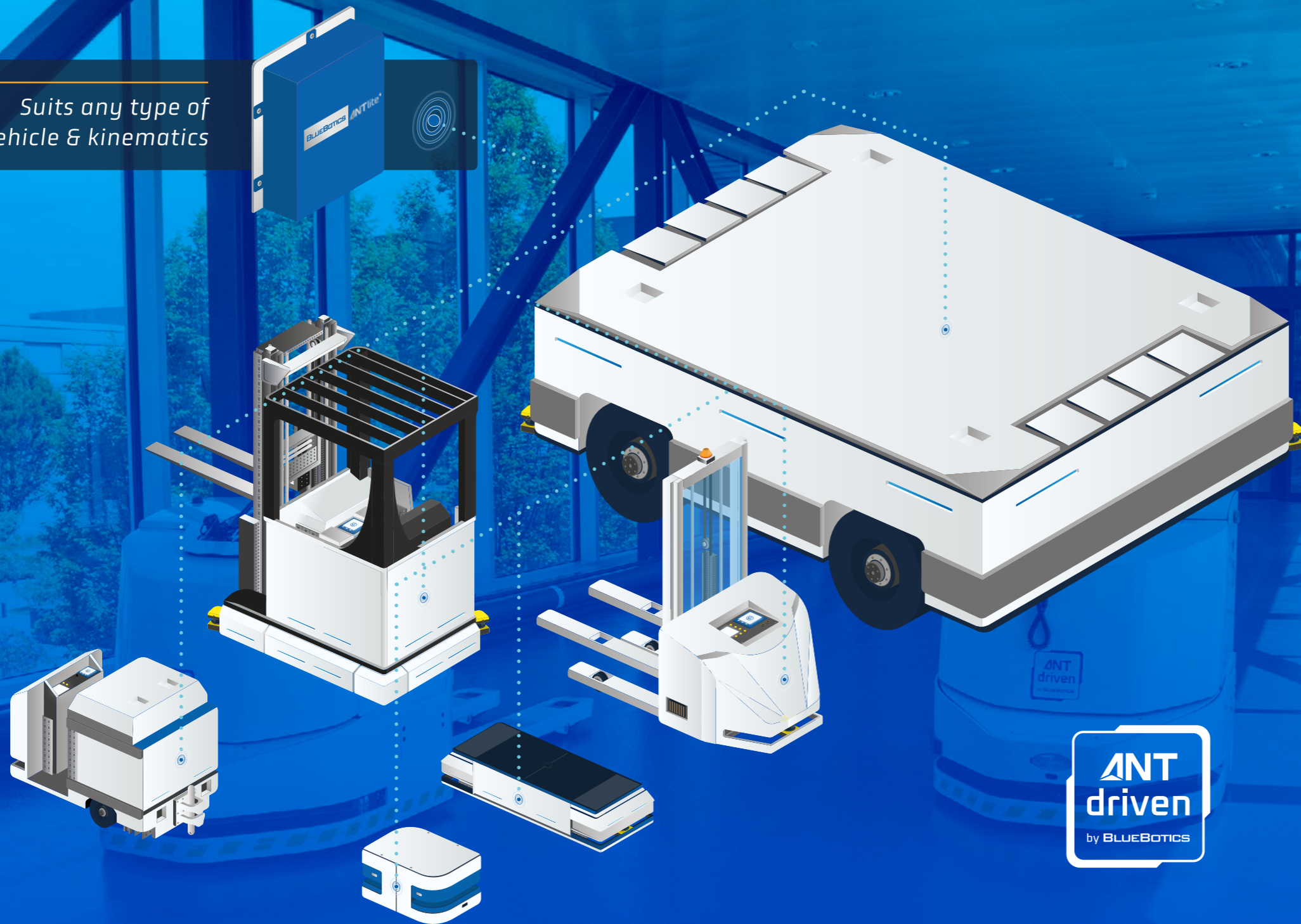


**ANT**  
Autonomous Navigation Technology

| Your vehicle, our navigation

**BLUEBOTICS**  
— Your Vehicle Navigation Partner

Suits any type of vehicle & kinematics



6,000+

ANT driven vehicles in operation

2,000+

end-user installations

150+

vehicle types automated

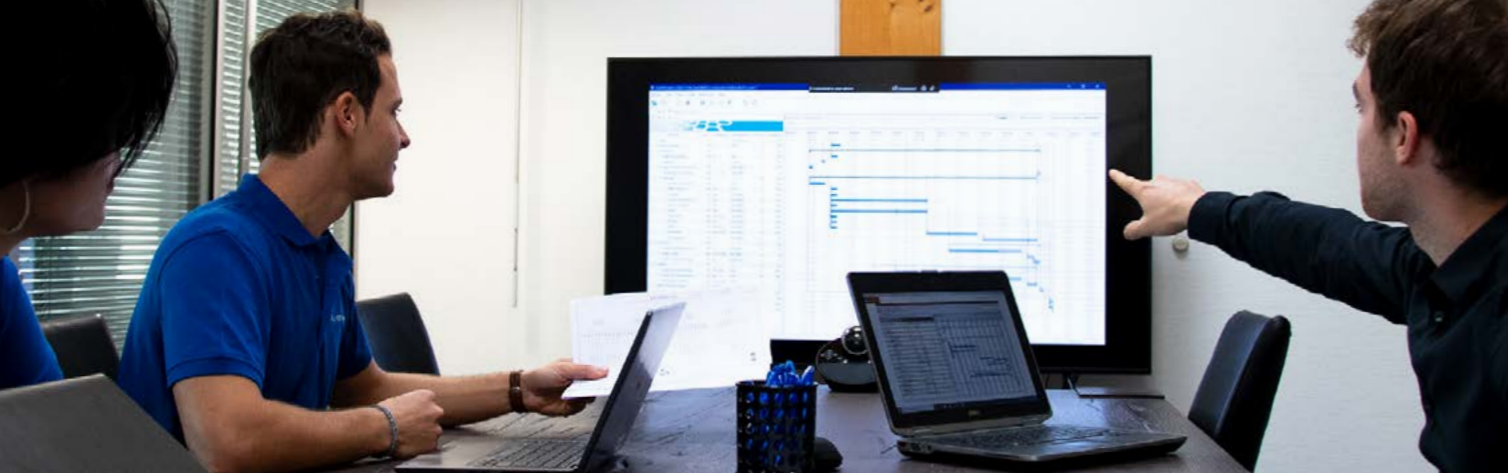
### NATURAL FEATURE NAVIGATION FOR YOUR AGV, AUTOMATED FORKLIFT OR MOBILE ROBOT

With more than two decades of natural navigation experience, vehicle automation is a challenge we understand deeply.

During this time, we have helped numerous companies to navigate this process, leading to the launch of dozens of ANT driven automated guided vehicles (AGVs), automated forklifts, autonomous mobile robots (AMRs) and service robots.

### Inside:

Meet BlueBotics	4
Introducing ANT navigation	6
ANT features	8
ANT solutions	10
Compare ANT solutions	15
How to commission ANT driven vehicles	16
How we can help	18
ANT technical specifications	19



## MEET YOUR AUTONOMOUS NAVIGATION PARTNER

At BlueBotics we help companies meet the challenge of vehicle automation. We provide the navigation technology and expert support they need to bring their AGV, automated forklift or mobile robot successfully to market.

When you partner with BlueBotics, our team works with you every step of the way to ensure our **Autonomous Navigation Technology (ANT)** is integrated successfully into your vehicle. Whatever it takes, we're by your side until it works.

### Communication

We value effective communication. Listening and understanding is key, then our goal is to always convey clear and constructive messages, with customers, partners and each other.

### Innovation

We are committed to continuous innovation that brings real-world value to our customers.

### Simplicity

Pioneering technology is only useful if it is simple to use. We strive to make our products (and team) as easy to work with as possible.

**24** YEARS  
OF  
NATURAL  
FEATURE  
NAVIGATION

Our team of experienced staff covers every skillset your business might require: from mechatronics, system design and autonomous navigation to commercial business development and marketing.

“BlueBotics’ ANT technology is very sound. Its ability to follow a path and follow it precisely was a game changer for us. And with the continuous improvements the team is making, the company has great potential. The way we’re working together, it’s effortless.”



Michael Marcum  
General Manager, Autonomous Vehicles  
Bastian Solutions | a Toyota Advanced Logistics company

Our products are not only engineered in Switzerland, they are also produced here. Together with our network of suppliers, we deliver precise Swiss Made solutions, which guarantee your vehicles perform perfectly, both now and in the future.



*At BlueBotics we've helped companies to develop autonomous vehicles and robots for over two decades.*





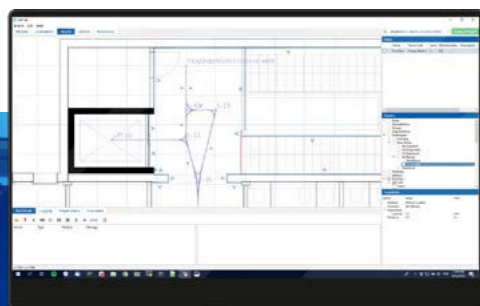
## INTRODUCING AUTONOMOUS NAVIGATION TECHNOLOGY (ANT)

ANT navigation technology is a flexible, accurate and highly robust solution that meets the evolving needs of vehicle producers and operators.

Based on 20 years of industry experience, ANT is simple to use and cost-effective to install and modify.



All BlueBotics products are FCC/CE certified.



**ANT lab [included]:**  
Configure vehicles & missions



**ANT server:**  
Manage missions & fleets

NATURAL FEATURE NAVIGATION FOR YOUR AGV,  
AUTOMATED FORKLIFT OR MOBILE ROBOT

- > Natural feature navigation
- > Accurate to  $\pm 1$  cm /  $\pm 1^\circ$
- > Minimal infrastructure changes (reflective stickers possible)
- > Vehicles commissioned in days, not weeks
- > Multi-brand fleet management

“After a week to prepare the map and pick/drop positions, we turned on our client’s fleet and were able to run full production the same day. We have 12 AGVs and 6 loading positions delivering to 80 unloading positions. The performance and stability of BlueBotics’ ANT lab software has really saved us a lot of time during commissioning.”



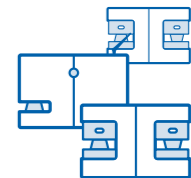
Kurtis Schram  
Application Developer  
Cimcorp North America



**Quick**  
to install  
and modify



**Accurate**  
to  
 $\pm 1$  cm /  $\pm 1^\circ$



**Scalable**  
fleets up to 300,  
any vehicle type



Comparing navigation technologies  
Join our expert team for an in-depth appraisal of today’s different autonomous navigation technologies.

[> WATCH THE WEBINAR](#)



### Embedded mission control

The transfer of mission data from computer to vehicle happens once (instead of commands being sent continuously from server to vehicle). This vastly reduces network requirements.



### Payload detectors

These functions enable the successful pick-up of pallets and racks, and the hitching of carts, even if staff place these payloads imprecisely.



### Full integration support

Our expert team of engineers supports you from project kick-off until you have a fully working ANT driven vehicle (including on-site).



### Optional: outdoor extension

Adds high-precision GNSS positioning to enable equally precise outdoor operations.

## WHAT FEATURES DOES ANT NAVIGATION INCLUDE?

**Autonomous Navigation Technology (ANT)** includes a wide range of features to automate your AGV, forklift or mobile robot. Each function has been designed to bring real-world value, based on the needs of customers around the world.



### Robust localization

ANT uses laser scanner data and odometry to localize the vehicle in the map, using permanent structures (features) in the environment acting as references. Accurate to  $\pm 1$  cm /  $\pm 1^\circ$ .



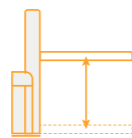
### Optimal vehicle control

Based on the X, Y and angle coordinates provided, ANT controls the vehicle's motion either directly or via the vehicle's PLC (ANT lite+ only).



### Obstacle avoidance option

Enables a vehicle to dynamically navigate around blockages, rather than waiting for them to be removed. This navigation mode suits applications where coverage is more important than efficiency (e.g. cleaning).



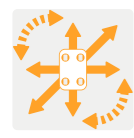
### Fork control

ANT lite+ enables advanced actions such as full control of a lift truck's forks by communicating either with a vehicle's PLC or the motor controller that controls the fork.



### Optimized path follower

ANT's virtual path following is efficient, accurate and repeatable, with the vehicle stopping in case of blockages. This navigation mode suits most industrial applications.



### Full kinematic support

ANT is compatible with all types of AGV, forklift and AMR kinematics including tricycle, differential, car-like (Ackermann) and omnidirectional.

## ADDITIONAL WITH ANT server



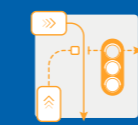
### Fleet management

ANT server selects and deploys the right vehicle for each mission, seamlessly coordinates vehicles at intersections, and provides operators with a complete overview of their fleet in real-time.



### Intelligent mission scheduling

Decides which vehicle to send on each mission, based on parameters you can configure.



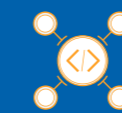
### Traffic control

ANT server's built-in traffic manager seamlessly coordinates the movement of different vehicles at locations such as intersections, doors, elevators etc.



### Battery charge management

Determines when and where a vehicle must go to charge its battery.



### API connection to WMS/MES/ERP

Manage missions and your wider fleet via your organization's existing software infrastructure via ANT server's dedicated API.



### Equipment interfacing

Use ANT server's API to interface with equipment such as automatic doors, elevators, palletizers, production machines and more.



### System monitoring

Visualize and monitor your AGV operation with ANT server's handy web interface for use with PC/tablet /smartphone etc.



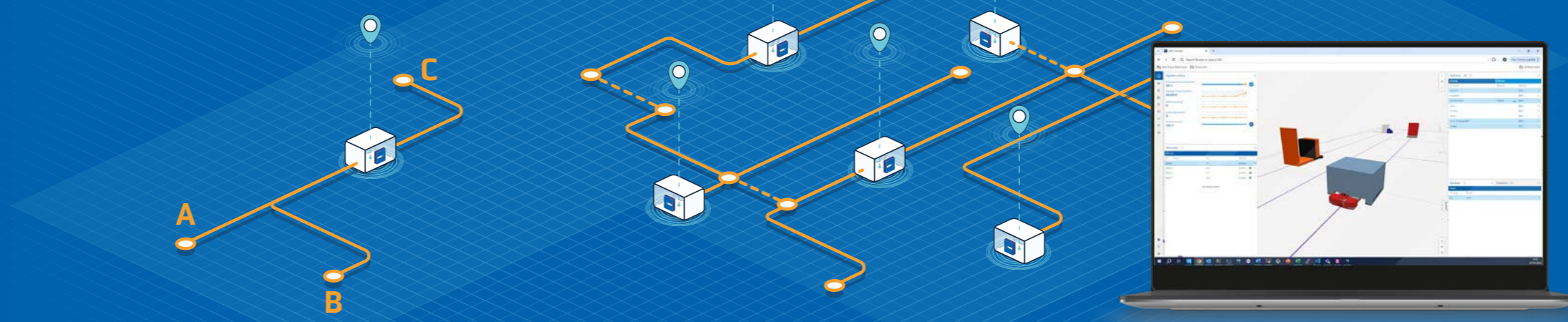
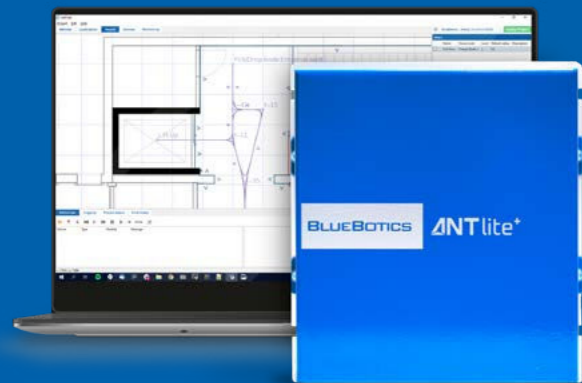
### Mission simulation

Ensure your operation runs smoothly from the start by simulating everything from individual AGV missions to full-scale fleet operations.

“The ANT product allowed Stöcklin to enter the AGV market with a competitive, flexible vehicle, which is installed in days.”



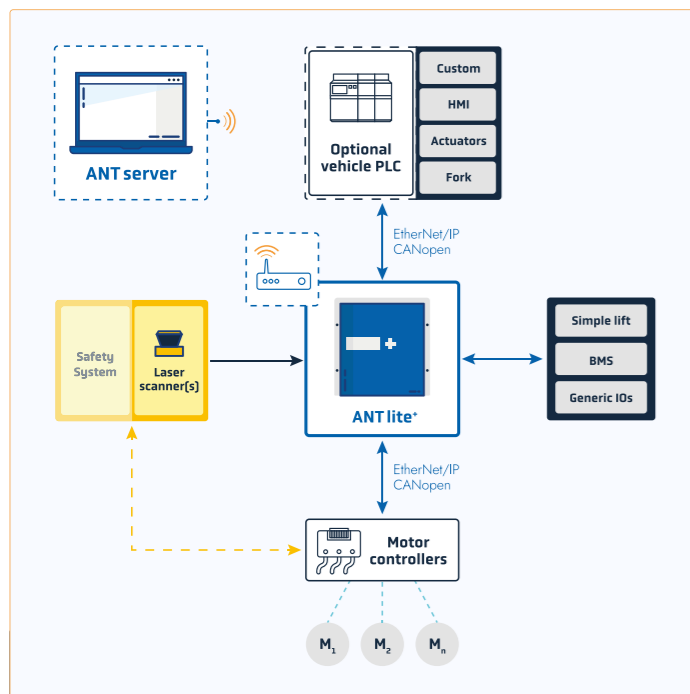
Valentin Adelfio  
Director Lift Trucks  
Stöcklin



## ANT lite+

POSITIONING & CONTROL

ANT lite+ is a vehicle control and positioning system for AGVs, automated forklifts and mobile robots. This complete natural feature navigation solution calculates the vehicle's position (localization), controls its motion, and interfaces directly with the vehicle's safety laser scanners.



ANT lite+ provides commands directly to a vehicle's motor controller or via the vehicle's PLC (e.g. to interface with specific devices).

### FULLY AUTOMATE YOUR VEHICLE

#### Positioning & control for:

- > Automated guided vehicles (AGVs)
- > Automated forklifts
- > Autonomous mobile robots (AMRs)
- > Service robots

#### Includes:



Every ANT navigation system is supplied with ANT lab, our proven vehicle and mission configuration software.

## ANT server

MISSION & FLEET MANAGEMENT

### FOR ANT lite+

ANT server is our advanced mission and fleet management software. Use it to manage and optimize your on-site operation (including traffic control).

#### Any vehicle. Any brand.

ANT server is a truly cross-platform solution. It can manage any AGVs, automated forklifts or mobile robots driven by ANT lite+, no matter what a vehicle's type, brand or kinematics.

- > Simulate vehicles and missions
- > Schedule missions
- > Control traffic automatically
- > Monitor your fleet in real-time
- > Manage the charging of vehicles
- > Interface with software (WMS/MES/ERP) and equipment (doors/elevators etc.)



### PUT YOUR AGVs TO WORK





# ANTloc<sup>+</sup>

## POSITIONING & EMULATION OF LINE FOLLOWING

ANT localization<sup>+</sup> is a positioning system for the upgrading of line following AGVs. It enables a vehicle to follow a virtual line using natural feature navigation, effectively replacing the antenna used to follow physical lines such as magnetic tape, inductive wire, tags etc.



# ANTloc

## POSITIONING

ANT localization is a vehicle positioning system for automated guided vehicles (AGVs), automated forklifts and mobile robots. It can also be used to track manual vehicles. ANT localization simply provides position coordinates to the main vehicle controller. Therefore, it suits vehicle makers who have their own control system.



### UPGRADE TO VIRTUAL LINE FOLLOWING

#### Positioning for:

- > Line following AGVs



### KNOW EXACTLY WHERE YOUR VEHICLE IS

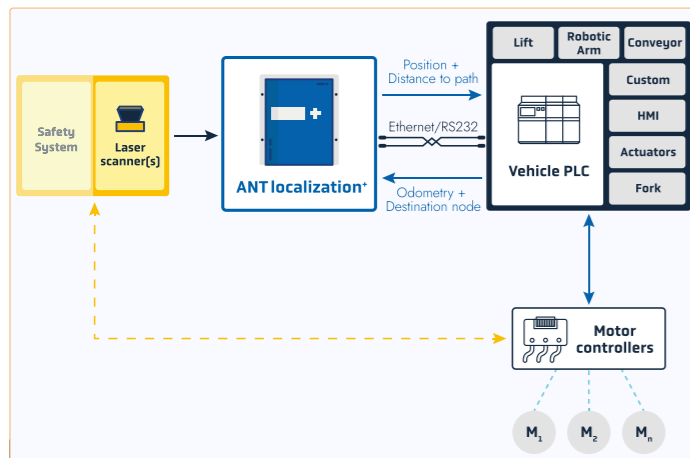
#### Positioning for:

- > Automated guided vehicles (AGVs)
- > Automated forklifts
- > Autonomous mobile robots (AMRs)
- > Service robots
- > Manual vehicles

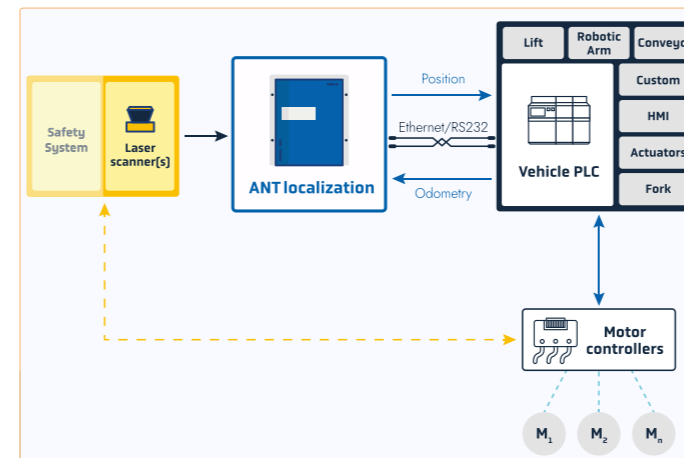
#### Includes:



Every ANT navigation system is supplied with ANT lab, our proven vehicle and mission configuration software.



ANT localization<sup>+</sup> estimates a vehicle's distance from the desired virtual line (offset). It then communicates this data directly to the PLC, as well as providing virtual tags and a recommended speed.

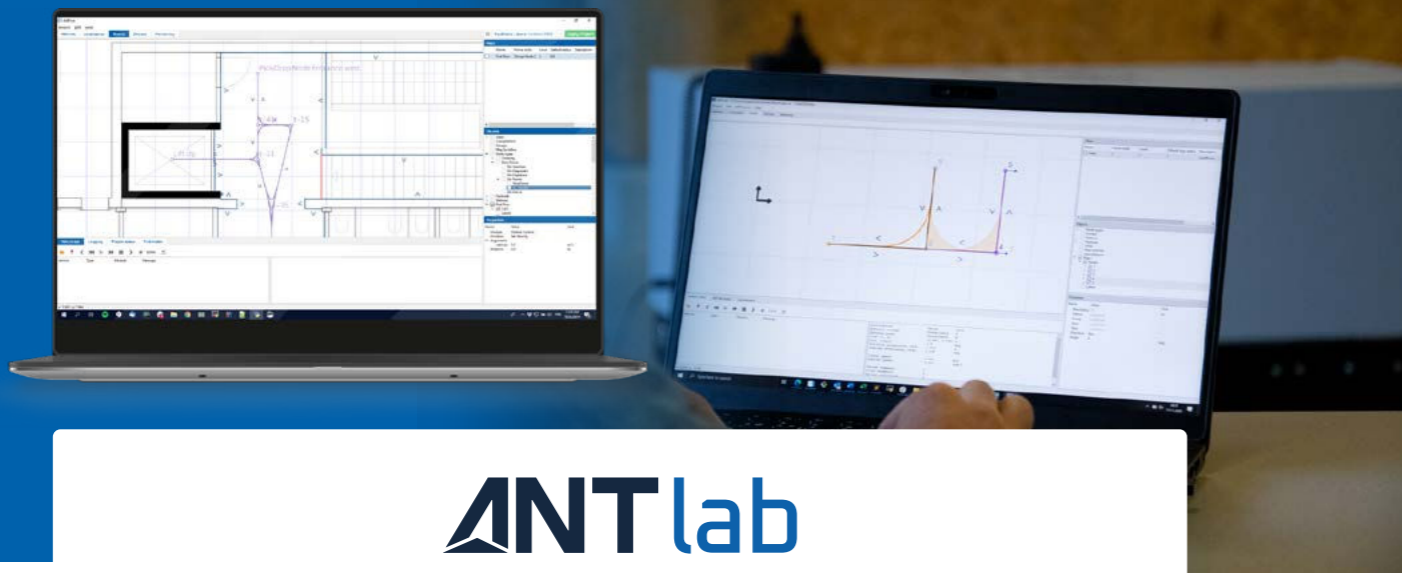


ANT localization provides a vehicle's coordinates directly to the PLC.

#### Includes:



Every ANT navigation system is supplied with ANT lab, our proven vehicle and mission configuration software.

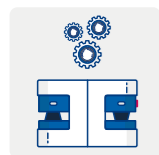


# ANTlab

## VEHICLE & MISSION CONFIGURATION

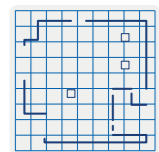
ANT lab is our proven vehicle and mission configuration software. Use it to configure and install your customers' AGVs. Then, in the future, use ANT lab to update their installations, modifying routes and actions as required.

### How it works



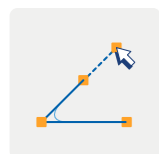
#### 1 Configure & calibrate your vehicle

Set your vehicle's parameters, then calibrate its laser scanner positions and odometry to ensure high accuracy.



#### 2 Create your map

Create the site map by driving your vehicle around manually. Then, clean this by removing dynamic objects, leaving only the permanent, static features your vehicle will use as references.

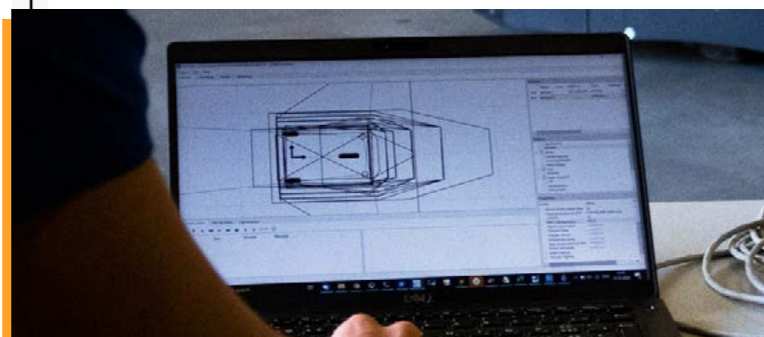


#### 3 Define routes & actions

Create your vehicle's routes, define actions (such as moving its forks), and configure devices to define how your vehicle interacts with chargers, elevators etc. If using ANT server, battery management strategies can also be defined. Traffic rules are configured automatically.

### CONFIGURE, INSTALL, DEPLOY

- > Configure & calibrate vehicles
  - > Map sites
  - > Create routes & actions (e.g. move forks)
  - > Configure devices (e.g. chargers, elevators etc.)
  - > Monitor & validate projects
- 
- > Included with every ANT product
  - > Free & regular updates

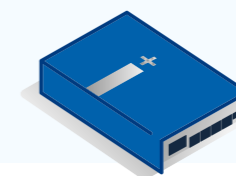


“BlueBotics’ technology is the most robust natural feature navigation software around. We couldn’t believe its potential, or the precision possible, until we saw it with our own eyes. And when integrating ANT into our forklifts, the support was excellent, simply the best.”

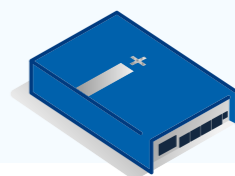


Thanassis Papaleloudis  
CEO  
LIFTCO E.E.

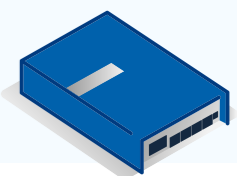
### COMPARE ANT PRODUCTS



ANTlite+



ANTloc+



ANTloc

	ANTlite+	ANTloc+	ANTloc
LOCALIZATION	✓	✓	✓
CONTROL	✓	✗	✗
EMULATION OF LINE FOLLOWING	✗	✓	✗
MISSION MANAGEMENT	✓	✗	✗
FLEET MANAGEMENT	✓ <small>[WITH ANT server]</small>	✗	✗
OUTDOOR OPERATION	✓ <small>[WITH ANT everywhere]</small>	✓ <small>[WITH ANT everywhere]</small>	✓ <small>[WITH ANT everywhere]</small>



Which ANT product do I need?

To identify the best ANT navigation system for your vehicle, try our online product finder tool.

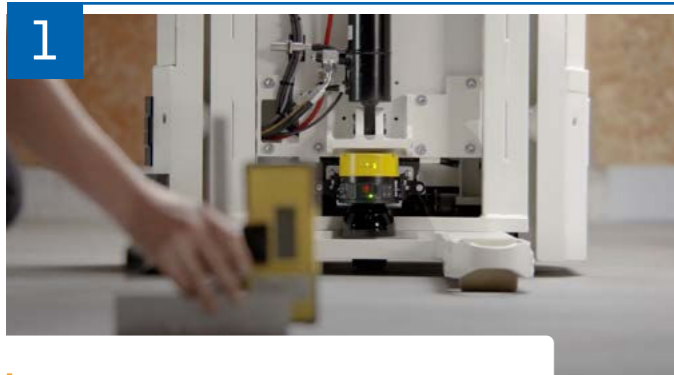
> [PRODUCT FINDER](#)





## HOW TO COMMISSION ANT DRIVEN VEHICLES

When it comes to making your customers happy and ensuring the profitability of your vehicle, quick and efficient commissioning (or installation) is the goal. With ANT this process is quick and simple, with minimal infrastructure changes required.



### 1 Calibrate your vehicle

When your ANT driven vehicle arrives at your customer's site, your team's first job will be to make sure its ANT navigation system properly understands the specific parameters of your vehicle. This step is important because a vehicle's components – such as its LiDAR laser scanners, used by ANT for positioning – can be easily nudged out of alignment during shipping.



### 2 Create your site map

Drive your AGV manually around the site. Our ANT lab software (included) records data from the vehicle's safety laser scanners, which is then used to generate a 2D map.



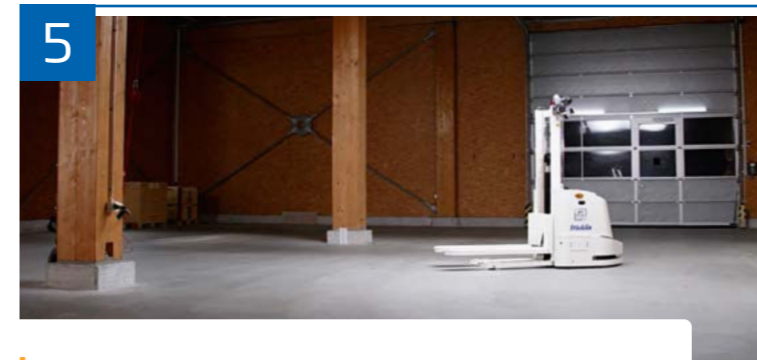
### 3 Clean your map

Then, 'clean' this map by removing any dynamic objects, leaving only permanent features such as walls, pillars, fixed equipment, etc. These 'references' will be used to calculate your vehicle's position, allowing it to navigate effectively.



### 4 Create your vehicle's routes

Now that your vehicles are calibrated and your site map is clean, you can plot the routes - the virtual paths - your robots will use to get around. The process in ANT lab is simple: first, create 'nodes', then join these together with 'links'.



### 5 Program your vehicle's actions

An action is a single task that is programmed to happen at a node's location, such as slowing down or raising a vehicle's forks. Custom actions are also available. Much of this work can be done in advance, potentially saving days of time on-site.



Installing an ANT driven vehicle in 5 steps

[> WATCH VIDEO](#)

“Mapping and routing with ANT lite+ have significantly sped up our commissioning process. One of our most successful projects involved deploying a fleet of AGVs for Toyota, the gold standard in automotive manufacturing and efficiency, an achievement that was made possible by BlueBotics' ANT server fleet manager. And the company's GNSS solution, which allows for precise outdoor navigation — something we couldn't achieve with our previous systems — has opened new application possibilities. Best of all, the support we've received throughout has been excellent.”

“

Joseph Cotterill  
Automation and Technology Installation Manager  
MasterMover

## HOW WE CAN HELP

Our proven collaboration process is flexible enough to suit every project's needs. Put simply, it breaks down into three key phases.



Get our detailed project guide

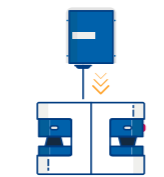
Explore how we will work with you to make your automated vehicle project a success.

[> DOWNLOAD GUIDE](#)



### Discovery

We discuss your needs to ensure our ANT navigation technology can bring value to your vehicle.



### Integration

This phase spans from kick-off until your company has a working ANT driven vehicle, including on-site support.



### Launch

We work with you to make sure your launch is a success, including on-site support at your first customer installation.

## Integration Package

Our expert team supports your vehicle's development every step of the way. This includes visiting your site during the integration of ANT into your vehicle, and supporting you at your customer's site the first time your vehicle is commissioned.

“By working with BlueBotics and using its ANT technology in our Eco-ProFleet AGVs, we gain a reliable navigation solution and our team can focus on our key business. The whole BlueBotics team has a great spirit and a great mindset, with a strong focus on common progress.”

Stefano Bell  
Product Manager  
Dürr

## ANT TECHNICAL SPECIFICATIONS

	ANTlite+	ANTloc+	ANTloc
<b>FUNCTIONALITY</b>	Positioning, control	Positioning, emulation of line following	Positioning
<b>VEHICLE COMPATIBILITY</b>			
Kinematics	Tricycle, differential, omnidirectional, car-like (Ackermann)	Tricycle, differential, omnidirectional, car-like (Ackermann)	Tricycle, differential, omnidirectional, car-like (Ackermann)
Maximal speed	Up to 3.5 m/s (7.8 mph)	Up to 5.0 m/s (11.2 mph)	Up to 5.0 m/s (11.2 mph)
<b>POSITIONING</b>			
Accuracy	± 1 cm/± 1°	± 1 cm/± 1°	± 1 cm/± 1°
Localization rate	5 Hz	Up to 20 Hz	Up to 20 Hz
<b>CONTROL</b>			
Obstacle avoidance rate	10 Hz	-	-
Path following rate	10 Hz	10 Hz (emulation)	-
<b>COMPATIBLE COMPONENTS</b>			
Safety laser scanners	Hokuyo UAM-05LP Idec SE2L Leuze RSL425, RSL445 Omron OS32C, OS33C SICK microScan3, nanoScan3, outdoorScan3, S300 Expert, S3000 Expert, TiM781S	Hokuyo UAM-05LP Idec SE2L Leuze RSL425, RSL445 Omron OS32C, OS33C SICK microScan3, nanoScan3, outdoorScan3, S300 Expert, S3000 Expert, TiM781S	Hokuyo UAM-05LP Idec SE2L Leuze RSL425, RSL445 Omron OS32C, OS33C SICK microScan3, nanoScan3, outdoorScan3, S300 Expert, S3000 Expert, TiM781S
Non-safety laser scanners	Hokuyo URM-40LC-EW Pepperl+Fuchs R2000 SICK LMS1xx, LMS500, LMS511 Heavy Duty, TiM571, TiM581, LRS4581R	Hokuyo URM-40LC-EW Pepperl+Fuchs R2000 SICK LMS1xx, LMS500, LMS511 Heavy Duty, TiM571, TiM581, LRS4581R	Hokuyo URM-40LC-EW Pepperl+Fuchs R2000 SICK LMS1xx, LMS500, LMS511 Heavy Duty, TiM571, TiM581, LRS4581R
Motor drives	CANopen, EtherNet/IP	-	-
User configurable I/Os	10 dig. in / 10 dig. out	-	-
<b>HARDWARE</b>			
Embedded computer	Industrial PowerPC	Industrial PowerPC	Industrial PowerPC
Operation voltage	24 VDC (20 VDC...30 VDC)	24 VDC (20 VDC...30 VDC)	24 VDC (20 VDC...30 VDC)
Power consumption	<20 W	<20 W	<20 W
Operating temperature	0°C to 60°C	0°C to 60°C	0°C to 60°C
Storage temperature	-25°C to 85°C	-25°C to 85°C	-25°C to 85°C
Relative humidity	5% to 95% (non-condensing)	5% to 95% (non-condensing)	5% to 95% (non-condensing)
IP rating	IP30	IP30	IP30
Certification	CE, FCC	CE, FCC	CE, FCC
Dimensions [WxHxL]	153 x 46 x 160 mm	134 x 30 x 160 mm	134 x 30 x 160 mm
Weight	0.85 kg	0.65 kg	0.65 kg

# BLUEBOTICS

— Your Vehicle Navigation Partner

## About us

At BlueBotics we help companies meet the challenge of vehicle automation. We provide the navigation technology and expert support they need to bring their AGV, automated forklift or mobile robot successfully to market.

**A ZAPI GROUP COMPANY**

## How to find us

### CONTACT US

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### HEADQUARTERS

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| Shanghai, China



Swiss  
Made

ISO 9001:2015  
certified